

ENCODER

EtherCAT Multiturn



Series 8.5868, 8.5888

Key-Features:

- Solid shaft: maximum diameter 10 mm
- Blind hollow shaft: maximum diameter 15 mm
- Housing diameter 58 mm
- Interface: EtherCAT, CAN over Ethernet
- Protection class up to IP67
- Total resolution up to 28 Bit
- Maximum revolution speed 9000 turns/min
- Temperature range -40...+80°C

Content:

Order Code2
Technical Data3
EtherCAT Interface4
Connection4
Technical Drawing5

Absolute encoders – multiturn

**Standard
mechanical multiturn, optical**

Sendix 5868 / 5888 (shaft / hollow shaft)

EtherCAT



The multiturn encoders Sendix 5868 and 5888 with second-generation EtherCAT interface and optical sensor technology are ideal for use in all applications with an EtherCAT interface.

The data communication is based on CAN over EtherNet and ideally suited for use in real time applications.

These encoders are available with a solid shaft up to a maximum of 10 mm or a blind hollow shaft up to 15 mm.



Mechanical drive



Safety-Lock™



High rotational speed



Temperature range
-40°...+80°C



High protection level



High shaft load capacity



Shock / vibration resistant



Magnetic field proof



Reverse polarity protection



Optical sensor



Surface protection salt spray-tested optional

Reliable

- EtherCAT conformance tested.
- Integration of the latest slave – EtherCAT stack from Beckhoff, Version 5.01.
- Ideally suited for use in harsh outdoor environments, thanks to IP67 protection and rugged housing construction.

Flexible

- Use of CoE (CAN over EtherNet).
- Genuine new position information as a result of minimal cycle time of 62.5 µs in the DC mode.
- Faster, easier error-free connection thanks to M12 connectors.
- Supports Hot Connect.

**Order code
Shaft version**

8.5868 . **XXB2** . **B2 12**
Type a b c d e



a Flange

- 1 = clamping flange, IP65 ø 58 mm [2.28"]**
- 3 = clamping flange, IP67 ø 58 mm [2.28"]
- 2 = synchro flange, IP65 ø 58 mm [2.28"]**
- 4 = synchro flange, IP67 ø 58 mm [2.28"]
- 5 = square flange, IP65 □ 63.5 mm [2.5"]
- 7 = square flange, IP67 □ 63.5 mm [2.5"]

b Shaft (ø x L), with flat

- 1 = 6 x 10 mm [0.24 x 0.39"]**¹⁾
- 2 = 10 x 20 mm [0.39 x 0.79"]**²⁾
- 3 = 1/4" x 7/8"
- 4 = 3/8" x 7/8"

c Interface / power supply

B = EtherCAT / 10 ... 30 V DC

Optional on request

- Ex 2/22
- surface protection salt spray tested

d Type of connection

removable bus terminal cover
2 = 3 x M12 connector, 4-pin

e Fieldbus profile

B2= EtherCAT with CoE (CAN over EtherNet)

**Order code
Hollow shaft**

8.5888 . **XXB2** . **B2 12**
Type a b c d e



a Flange

- 1 = with spring element, long, IP65
- 2 = with spring element, long, IP67
- 3 = with stator coupling, IP65 ø 65 mm [2.56"]
- 4 = with stator coupling, IP67 ø 65 mm [2.56"]
- 5 = with stator coupling, IP65 ø 63 mm [2.48"]**
- 6 = with stator coupling, IP67 ø 63 mm [2.48"]

b Blind hollow shaft

- (insertion depth max. 30 mm [1.18"])
- 3 = ø 10 mm [0.39"]
- 4 = ø 12 mm [0.47"]**
- 5 = ø 14 mm [0.55"]
- 6 = ø 15 mm [0.59"]
- 8 = ø 3/8"
- 9 = ø 1/2"

c Interface / power supply

B = EtherCAT / 10 ... 30 V DC

Optional on request

- Ex 2/22
- surface protection salt spray tested

d Type of connection

removable bus terminal cover
2 = 3 x M12 connector, 4-pin

e Fieldbus profile

B2= EtherCAT with CoE (CAN over EtherNet)

1) Preferred type only in conjunction with flange type 2.
2) Preferred type only in conjunction with flange type 1.

Absolute encoders – multiturn

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Mounting accessory for hollow shaft encoders	Dimensions in mm [inch]	Order no.
Cylindrical pin, long for flange with spring element (flange type 1 + 2)	with fixing thread 	8.0010.4700.0000
Connection technology		Order no.
Cordset, pre-assembled	M12 male connector with external thread for port IN and port OUT, 4-pin 2 m [6.56'] M12 female connector with coupling nut for power supply, 4-pin 2 m [6.56']	K4P2M-S-M12-CAT K4P2M-S-M12

Technical data	
Mechanical characteristics	
Maximum speed	IP65 up to 70°C [158°F] 9000 min ⁻¹ , 7000 min ⁻¹ (continuous) IP65 up to T _{max} 7000 min ⁻¹ , 4000 min ⁻¹ (continuous) IP67 up to 70°C [158°F] 8000 min ⁻¹ , 6000 min ⁻¹ (continuous) IP67 up to T _{max} 6000 min ⁻¹ , 3000 min ⁻¹ (continuous)
Starting torque - at 20°C [68°F]	IP65 < 0.01 Nm IP67 < 0.05 Nm
Mass moment of inertia	shaft version 3.0 x 10 ⁻⁶ kgm ² hollow shaft version 7.5 x 10 ⁻⁶ kgm ²
Load capacity of shaft	radial 80 N axial 40 N
Weight	approx. 0.54 kg [19.05 oz]
Protection acc. to EN 60529	housing side IP67 shaft side IP65, opt. IP67
Working temperature range	-40°C ... +80°C [-40°F ... +176°F]
Material	shaft/hollow shaft stainless steel flange aluminum housing zinc die-cast
Shock resistance acc. to EN 60068-2-27	2500 m/s ² , 6 ms
Vibration resistance acc. to EN 60068-2-6	100 m/s ² , 55 ... 2000 Hz
Electrical characteristics	
Power supply	10 ... 30 V DC
Power consumption (no load)	max. 120 mA
Reverse polarity protection of the power supply	yes
UL approval	file 224618
CE compliant acc. to	EMC guideline 2014/30/EU RoHS guideline 2011/65/EU
Interface characteristics EtherCAT	
Resolution singleturn	1 ... 65535 (16 bit), scalable default: 8192 (13 bit)
Number of revolutions (multiturn)	max. 4096 (12 bit) scalable only via the total resolution
Total resolution	1 ... 268.435.456 (28 bit), scalable default: 33.554.432 (25 bit)
Code	binary
Protocol	EtherNet / EtherCAT
Diagnostic LED (red)	
LED is ON with the following fault conditions: Sensor error (internal code or LED error), low voltage, over-temperature	
Run LED (green)	
LED is ON with the following conditions: Preop-, Safeop and Op-State (EtherCAT status machine)	
2 x Link LEDs (yellow)	
LED is ON with the following conditions (port IN and port OUT): Link detected	
Modes	
Freerun, distributed clock	

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General information about CoE (CAN over EtherNet)

The EtherCAT encoders support the CANopen communication profile according to DS301. In addition device-specific profiles like the encoder profile DS406 are available.

Scaling, preset values, limit switch values and many other parameters can be programmed via the EtherCAT bus.

When switching the device on, all parameters are loaded from an EEPROM, where they were saved previously to protect them against power-failure.

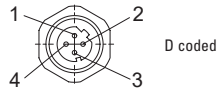
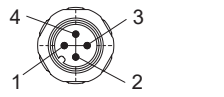
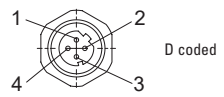
The following output values may be combined as PDO (PDO mapping): **position**, **speed**, **temperature values** and **working area state** as well as other process values.

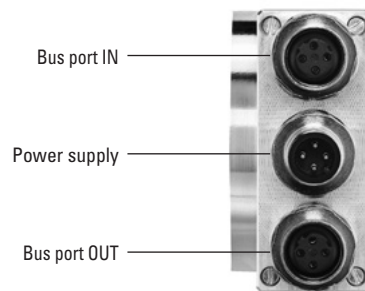
CANopen encoder profile 3.2.10 CoE (CAN over EtherNet)

The following parameters are programmable:

- Position update time of 62.5 µs.
- EtherCAT certificate of conformity.
- Speed with sign.
- Four units for speed calculation: steps/sec, steps/100 ms, steps/10 ms, min⁻¹.
- Time stamp as system time at the point in time when the position is read out.
- Two working area state registers.
- Along with the scaled position, the raw data – position as process value – is also mappable.
- Dynamic mapping.
- Gating time: setting of the time interval, via which the speed value can be interpolated.
- Sensor temperature in degrees Celsius.
- Comprehensive plausibility test when downloading parameters to the encoder.
- Alarm and warning messages.
- User interface with visual display of bus and fault status – 4 LEDs.
- Extended error management for position sensing with integrated temperature control.
- Implementation of the latest CANopen profile 3.2.10 from the 18th February 2011.
- Hot-Connect – Support for rapid change of Bus-topology.

Terminal assignment bus

Interface	Type of connection	Function	M12 connector, 4-pin					Diagram
			Signal:	Transmit data+	Receive data+	Transmit data -	Receive data -	
B	2 (3 x M12 connector)	Bus Port IN	Signal:	Transmit data+	Receive data+	Transmit data -	Receive data -	
			Abbreviation:	TxD+	RxD+	TxD-	RxD-	
			Pin:	1	2	3	4	
		Power supply	Signal:	Voltage +	–	Vo age –	–	
			Abbreviation:	+ V	–	0 V	–	
			Pin:	1	2	3	4	
		Bus Port OUT	Signal:	Transmit data+	Receive data+	Transmit data -	Receive data -	
			Abbreviation:	TxD+	RxD+	TxD-	RxD-	
			Pin:	1	2	3	4	



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EtherCAT

Dimensions shaft version, with removable bus terminal cover

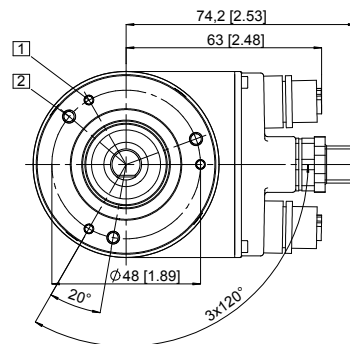
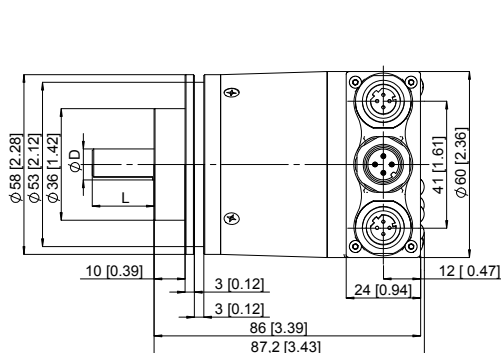
Dimensions in mm [inch]

Clamping flange, \varnothing 58 [2.28]

Flange type 1 and 3

- 1 3 x M3, 6.0 [0.24] deep
- 2 3 x M4, 8.0 [0.31] deep

D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h7	7/8"
3/8"	h7	7/8"

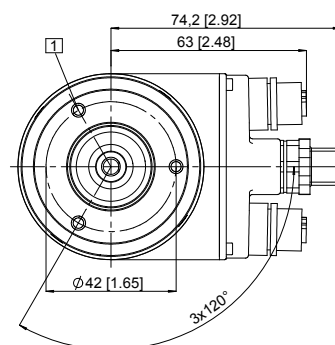
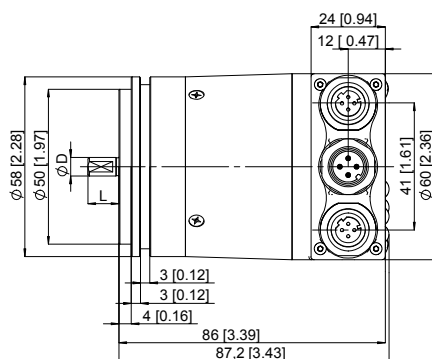


Synchro flange, \varnothing 58 [2.28]

Flange type 2 and 4

- 1 3 x M4, 6.0 [0.24] deep

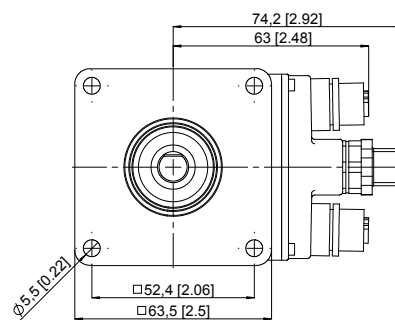
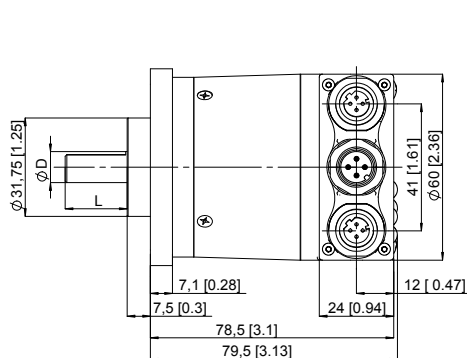
D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h7	7/8"
3/8"	h7	7/8"



Square flange, \square 63.5 [2.5]

Flange type 5 and 7

D	Fit	L
6 [0.24]	h7	10 [0.39]
10 [0.39]	f7	20 [0.79]
1/4"	h7	7/8"
3/8"	h7	7/8"



Absolute encoders – multiturn

**Standard
mechanical multiturn, optical**

Sendix 5868 / 5888 (shaft / hollow shaft)

EtherCAT

Dimensions hollow shaft version (blind hollow shaft), with removable bus terminal cover

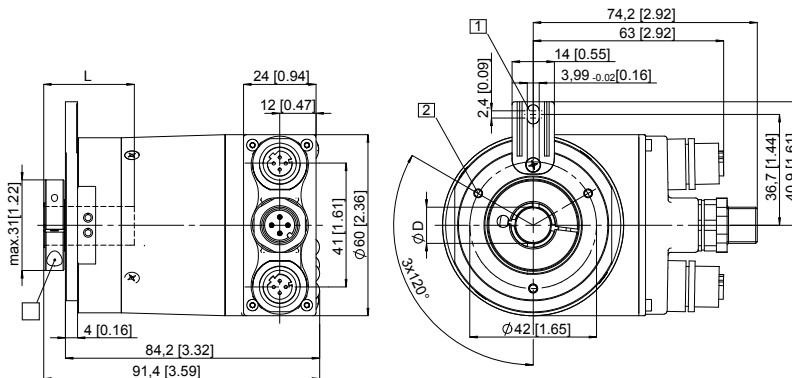
Dimensions in mm [inch]

Flange with spring element, long Flange type 1 and 2

- 1 Slot spring element recommendation: cylindrical pin DIN 7, ϕ 4 [0.16]
- 2 3 x M3, 5.5 [0.22] deep
- 3 Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft

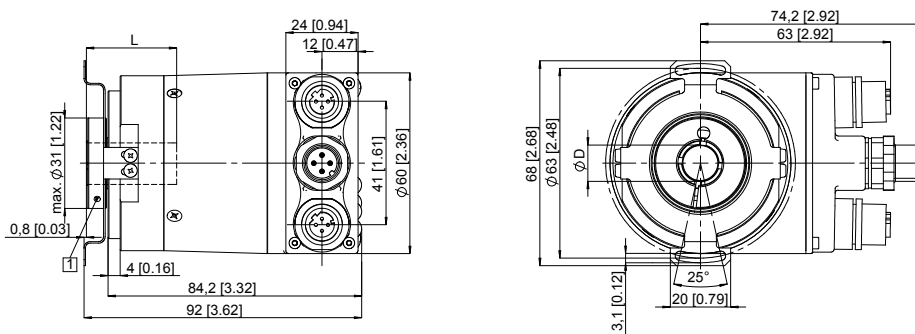


Flange with stator coupling, ϕ 63 [2.48] Flange type 5 and 6

- 1 Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft

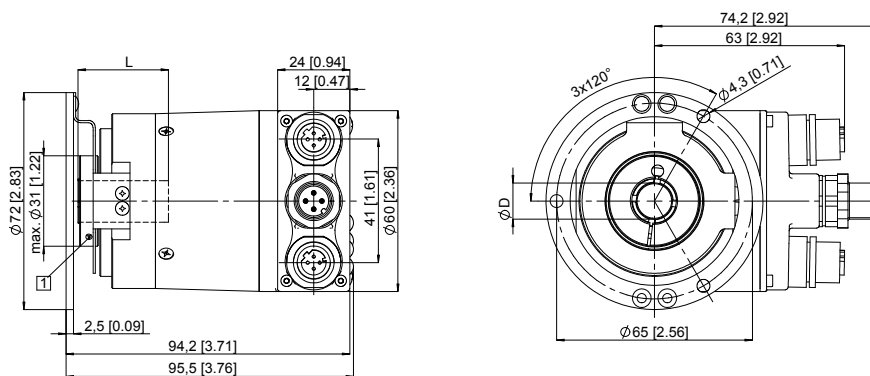


Flange with stator coupling, ϕ 65 [2.56] Flange type 3 and 4

- 1 Recommended torque for the clamping ring 0.6 Nm

D	Fit	L
10 [0.39]	H7	30 [1.18]
12 [0.47]	H7	30 [1.18]
14 [0.55]	H7	30 [1.18]
15 [0.59]	H7	30 [1.18]
3/8"	H7	30 [1.18]
1/2"	H7	30 [1.18]

L = insertion depth max. blind hollow shaft



Subject to change without prior notice.

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